

Solid shaft with synchro flange Magnetic single- or multiturn encoders 14 bit ST / 18 bit MT

### Overview

- Encoder single- or multiturn / SSI
- Precise magnetic sensing
- Angular accuracy up to ±0.15°
- Resolution max. 32 bit (14 bit ST, 18 bit MT)
- Additional incremental signals
- Clock frequency up to 2 MHz
- High protection up to IP 67
- High resistance to shock and vibrations



Technical data		
Technical data - electrical ratings		
Voltage supply	4.530 VDC (SSI, SSI + TTL/RS422) 5.530 VDC (SSI + HTL/Push-pull)	
Consumption typ.	60 mA (5 VDC, w/o load) 20 mA (24 VDC, w/o load)	
Initializing time	≤ 170 ms after power on	
Data currency	Typ. 2 µs (cyclic request)	
Interface	SSI + incremental	
Function	Multiturn Singleturn	
Operating mode	Linear feedback shift register (on request)	
Steps per revolution	≤16384 / 14 bit	
Number of revolutions	≤262144 / 18 bit	
Absolute accuracy	±0.15 ° (+20 ±15 °C) ±0.25 ° (-40+85 °C)	
Sensing method	Magnetic	
Code	Gray or binary	
Code sequence	CW: ascending values with clockwise sense of rotation; looking at flange	
Inputs	SSI clock: Linereceiver RS422 Zero setting input Counting direction	
Output stages	SSI data: Linedriver RS422 Incremental: linedriver RS422 or push- pull (option)	
Incremental output	1024, 2048, 4096 ppr (other on request)	
Output signals	A+, A-, B+, B-	
Output frequency	≤350 kHz	

Technical data - electrical ratings		
Interference immunity	EN 61000-6-2	
Emitted interference	EN 61000-6-4	
Diagnostic function	DATAVALID (on request)	
Approval	UL approval / E217823	
Technical data - mechanical design		
Size (flange)	ø36 mm	
Shaft type	ø10 x 16 mm, solid shaft with flat	
Flange	Synchro flange	
Protection EN 60529	IP 65 (without shaft seal) IP 67 (with shaft seal)	
Operating speed	≤6000 rpm	
Starting torque	≤2 Ncm (+20 °C, IP 65) ≤2.5 Ncm (+20 °C, IP 67)	
Moment of inertia	15.38 gcm <sup>2</sup>	
Admitted shaft load	≤40 N axial ≤80 N radial	
Material	Housing: steel zinc-coated Flange: aluminium Shaft: stainless steel	
Operating temperature	-40+85 °C (see general information)	
Relative humidity	95 %	
Resistance	EN 60068-2-6 Vibration 30 g, 10-2000 Hz EN 60068-2-27 Shock 500 g, 1 ms	
Weight approx.	170 g	
Connection	Flange connector M12, 8-pin Flange connector M12, 12-pin Cable 2 m	

### **Optional**

Protection against corrosion CX (C5-M)

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### **General information**

Self-heating interrelated to speed, protection, attachment method and ambient conditions as well electronics and supply voltage must be considered for precise thermal dimensioning. Self-heating is supposed to approximates 3 K (IP 65 protection) respectively 8 K (IP 67 protection) per 1000 rpm. Operating the encoder close to the maximum limits requires measuring the real prevailing temperature at the encoder flange.

### **Terminal assignment**

# Cable / Flange connector M12, 8-pin for connection reference -L and -B

Pin	Core color	Signals	Description
1	white	0 V	Supply voltage
2	brown	+Vs	Supply voltage
3	green	Clock+	Clock signal
4	yellow	Clock-	Clock signal
5	grey	Data+	Data signal
6	pink	Data-	Data signal
7	blue	SET	Zero setting input
8	red	DIR	Counting direction input*

Screen connected to housing

Cable data: 4 x 2 x 0.14 mm<sup>2</sup>, twisted in pairs



Male, A-coded

### Cable / Flange connector M12, 12-pin

for connection reference -L and -K

Pin	Core color	Signals	Description
1	brown	+Vs	Supply voltage
2	blue	SET	Zero setting input
3	white	0 V	Supply voltage
4	green	Clock+	Clock signal
5	pink	Data-	Data signal
6	yellow	Clock-	Clock signal
7	black	A+	Incremental signal
8	grey	Data+	Data signal
9	red	DIR	Counting direction input*
10	violet	A-	Incremental signal
11	grey/pink	B+	Incremental signal
12	red/blue	B-	Incremental signal
Screen	connected to h	ousing	

Cable data: 6 x 2 x 0.14 mm<sup>2</sup>, twisted in pairs



Male, A-coded

### \* Not applicable by option: DATAVALID

### **Terminal significance**

SET Zero setting.

Input for zero setting at any position.

The zero setting operation is triggered by a high pulse and has to be in line with the selected direction

of rotation (DIR).

Impulse duration >100 ms.

Connect to 0 V after zero setting for maximum

interference immunity.

DIR Counting direction input.

The input is standard on high. For maximum interference immunity connect to +Vs respectively

0 V depending on counting direction.

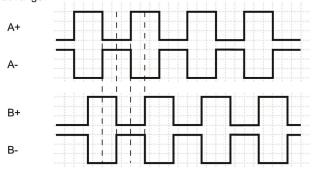
CW HIGH - CCW LOW

(Version with DATAVALID does not include the

counting directon input).

### **Output signals**

Incremental signals: clockwise rotating direction when looking at flange.



### Trigger level

Control inputs	Input circuit	
Maximal	0+Vs	
Input level Low	<1 V	
Input level High	>2.1 V	

### RS422

Output level High	>2.3 V
Output level Low	<0.5 V
Load	<20 mA

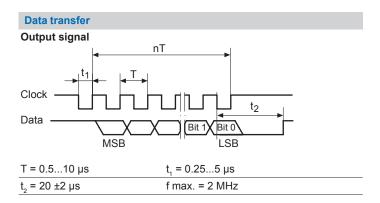
### Push-pull

Output level High	≥+VS -2.2 V	
Output level Low	<0.7 V	
Load	<20 mA	

Applies to standard cable lengths up to 2 m, for longer cables the voltage drop must be taken into account.

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### Data acquisition time ta

Following timing of the SSI Masters is the requirement for a data refresh rate of typ. 2 μs. If this is not fulfilled the data refresh rate is <50 μs. ta <5000 µs

ta jitter <±2 μs Clock Data

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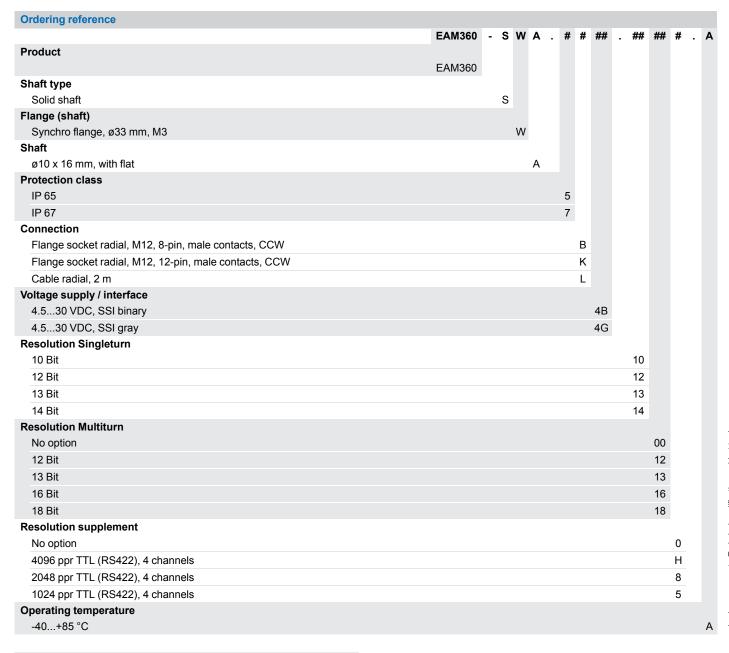
# Dimensions 53 21 9 26 ±0.2 9 X With cable 53 21 9 8 With flange connector M12, radial

### Absolute encoders/MAGRES

## EAM360-S - SSI

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### Accessories

### Mounting accessories

10106004

Clamp set ø10 mm